

Start-up for Procedures VAV Controller with Induction Damper

TEC-0108.11

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Verifying Power to Controller

NOTE: Update each controller at the field panel immediately after you complete the controller start-up procedures, and have made all other changes to the controller's point database including balancing, tuning, etc.

Verify that the VAV with Induction Damper is powered up. Check that the BST LED on the controller is flashing. If the BST LED does not flash on/off once per second, then refer to the *APOGEE Automation Service Procedures* on InfoLink for troubleshooting information.

NOTE: The Controller Interface Software (CIS) used with the VAV with Induction Damper Firmware (Revision VI10 or higher) must be Rev. 2.0 or greater. Voyager's point database may also be used for start-up.

Enabling Supply Damper Actuator

Using the portable operator's terminal, follow these steps to set the supply damper actuator running time:

1. Verify APPLICATION (Point 2) is set to **2091** (slave mode).
2. Display the STARTUP report.
3. Set the MTR1 TIMING (Point 51) to the correct running time of the supply damper actuator. Refer to *Table 1*.

Table 1. Damper Actuator Run Time.

Damper Actuator	Setting (seconds)	
	50 Hz	60 Hz
349-0101	106	88
GDE 131.1U	108	90
GDE 131.1P	108	90
GLB 131.1P	150	125
¹ GBB 171.1U	150	150
² GDE 161.1P	108	90
² GLB 161.1P	150	125

¹ GBB 171.1U run time is independent of Hz.

² Analog output 0-10V.

See the Manufacturer Installed Controls (MIC) web page on Landscape (<http://landscape.us.abatos.com/mic/>) for specific manufacturers' damper opening details (90°/60°/etc.).

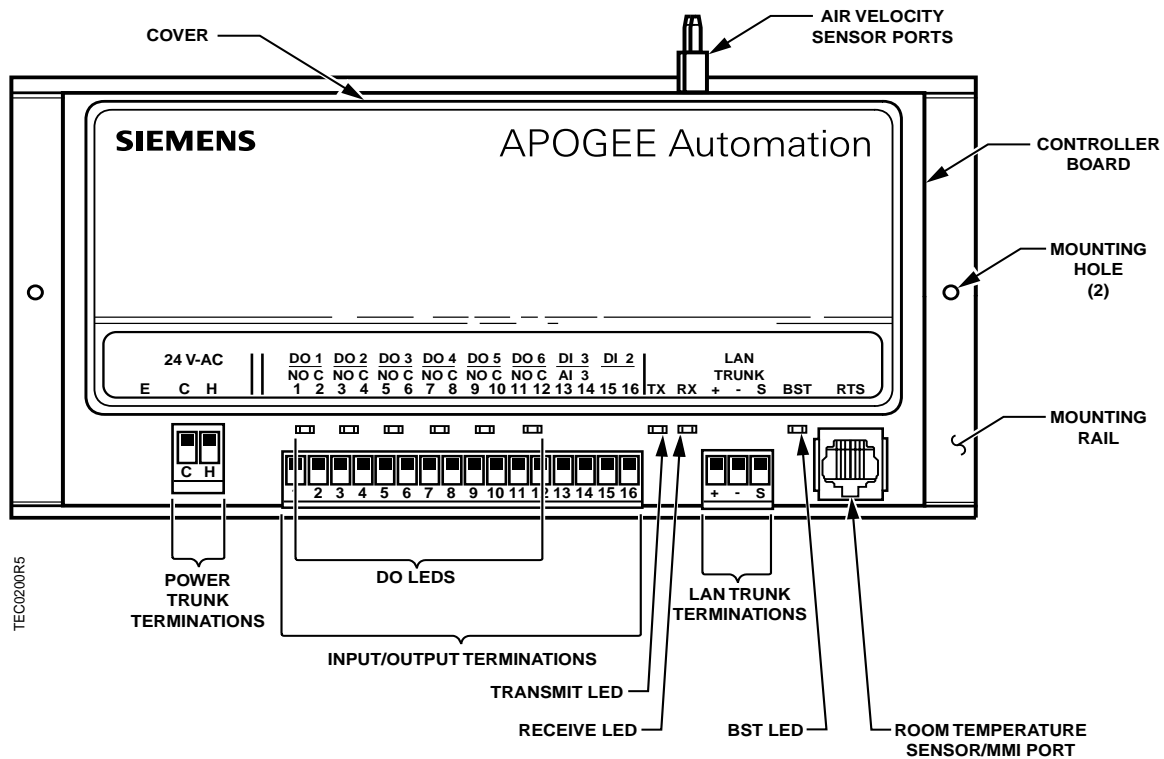


Figure 1. VAV with Induction Damper.

4. If the supply damper rotation angle is a value other than 90°, then set the DMPR ROT ANG (Point 56) to the appropriate value.
5. Enable the supply damper actuator by setting the MTR SETUP (Point 58) to 1. Verify that the damper closes completely. If it does not close completely, reverse the action of the damper actuator by setting MTR SETUP to 3.

If the supply damper still does not close completely, then the actuator has been installed or setup incorrectly. Refer to the damper actuator installation instructions, setup information, Table 2, or the *APOGEE Automation Service Procedures* on InfoLink for more information.

Table 2. Motor Enable/Reverse Values for MTR SETUP (Point 58).

	Motor 1 Enabled			Motor 1 Enabled and Reversed			Motor 1 Not Used		
	Motor 2 Not Used	Motor 2 Enabled	Motor 2 Enabled and Reversed	Motor 2 Not Used	Motor 2 Enabled	Motor 2 Enabled and Reversed	Motor 2 Not Used	Motor 2 Enabled	Motor 2 Enabled and Reversed
Motor 3 Not Used	1	5	13	3	7	15	0	4	12
Motor 3 Enabled	17	21	29	19	23	31	16	20	28
Motor 3 Enabled and Reversed	49	53	61	51	55	63	48	52	60

Enabling Valve Actuator

If applicable, then follow these steps to enable the valve actuator:

1. Set the MTR2 TIMING (Point 55) to the correct running time of the valve actuator. Refer to Table 3.

Table 3. Valve Actuator Run Time.

Valve Actuator	Setting (seconds)	
	50 Hz	60 Hz
SSB81U (Powermite – MZ Series)	180	150
SQS 82	155	130
SQS 65U (analog output 0 to 10V)	35	30
SQS 65.5U (analog output 0 to 10V)	35	30
SSB 61U (analog output 0 to 10V)	N/A	150

2. Enable the valve actuator by changing the MTR SETUP (Point 58) as follows:
 - If a supply damper actuator is present and is enabled (MTR SETUP = 1), then also enable the valve actuator by changing MTR SETUP to 5.
 - If a supply damper actuator is present, enabled, and reverse acting (MTR SETUP = 3), then also enable the valve actuator by changing MTR SETUP to 7.
3. Verify that the valve closes and remains closed. If the valve does not close, then reverse the action of the valve actuator by changing MTR SETUP as follows:
 - If the supply damper actuator is enabled, then change MTR SETUP to 13.

- If the supply damper actuator is enabled and reverse acting, then change MTR SETUP to **15**.

Enabling Induction Damper Actuator

Follow these steps to enable the induction damper actuator:

1. Set the MTR3 TIMING (Point 39) to the correct running time of the induction damper actuator. Refer to *Table 4*.

Table 4. Damper Actuator Run Time.

Damper Actuator	Setting (seconds)	
	50 Hz	60 Hz
349-0101	106	88
GDE 131.1U	108	90
GDE 131.1P	108	90
GLB 131.1P	150	125
¹ GBB 171.1U	150	150
² GDE 161.1P	108	90
² GLB 161.1P	150	125

¹ GBB 171.1U run time is independent of Hz.

² Analog output 0-10V.

See the Manufacturer Installed Controls (MIC) web page on Landscape (<http://landscape.us.abatos.com/mic/>) for specific manufacturers' damper opening details (90°/60°/etc.).

2. Enable induction damper actuator by changing the MTR SETUP (Point 58) as follows:
 - If a supply damper actuator is present and is enabled (MTR SETUP = 1), then enable the induction damper actuator by changing MTR SETUP to **17**.
 - If a supply damper actuator is present, enabled, and reverse acting (MTR SETUP = 3), then enable the induction damper actuator by changing MTR SETUP to **19**.
 - If a supply damper and a valve actuator are both present, enabled (MTR SETUP = 5), then enable the induction damper actuator by changing MTR SETUP to **21**.
 - If a supply damper actuator is present and is enabled, and a valve actuator is present, enabled, and reverse acting (MTR SETUP = 13), then enable the induction damper actuator by changing MTR SETUP to **29**.
 - If a supply damper actuator is present, enabled, reverse acting, and a valve actuator is present and is enabled (MTR SETUP = 7), then enable the induction damper actuator by changing MTR SETUP to **23**.

- If a supply damper and a valve actuator are both present, enabled, and reverse acting (MTR SETUP = 15), then enable the induction damper actuator by changing MTR SETUP to **31**.
3. Verify that the induction damper actuator closes and remains closed when commanded. If the induction damper does not close, then reverse the action of the induction damper actuator by adding the value 32 to the MTR SETUP.

If the induction damper actuator still does not close completely, then the actuator has been installed incorrectly. Refer to the valve actuator installation instructions, setup information, Table 5, or the *APOGEE Automation Service Procedures* on InfoLink for more information.

Table 5. Motor Enable/Reverse Values for MTR SETUP (Point 58).

	Motor 1 Enabled			Motor 1 Enabled and Reversed			Motor 1 Not Used		
	Motor 2 Not Used	Motor 2 Enabled	Motor 2 Enabled and Reversed	Motor 2 Not Used	Motor 2 Enabled	Motor 2 Enabled and Reversed	Motor 2 Not Used	Motor 2 Enabled	Motor 2 Enabled and Reversed
Motor 3 Not Used	1	5	13	3	7	15	0	4	12
Motor 3 Enabled	17	21	29	19	23	31	16	20	28
Motor 3 Enabled and Reversed	49	53	61	51	55	63	48	52	60

Setting Application

NOTE: If you are going to enter an LCTLR point at the field panel, then keep track of the application, override time, controller address, duct shape, and duct dimensions you enter at the portable operator's terminal. You will be required to enter these values again at the field panel.

Set the APPLICATION (Point 2) to the appropriate VAV with Induction Damper application. Refer to *Table 6* for application names and Points.

Table 6. VAV with Induction Damper Applications.

Application	Revision VI10 or Higher
VAV with Hot Water Reheat and Induction Damper	2333
Slave Mode	2091

After you set the application, the controller will go through a shut-down/load sequence as it switches from slave mode to the application selected. After the application loads, the OVERVIEW report appears and the calibration cycle begins.

Confirming Air Velocity Sensor Calibration

The air velocity sensor calibration cycle takes from 2 to 5 minutes to complete. The air damper closes during calibration.

At the start of the calibration cycle, the controller automatically sets CAL AIR (Point 94) to YES. When the cycle is complete, it sets CAL AIR to NO.

NOTE: The damper is commanded closed to get a zero airflow reading during calibration.

It is not necessary to wait until the calibration cycle is complete (CAL AIR is set to NO) before continuing with this start-up procedure.

Selecting Automatic Calibration Option

In order to choose the most efficient method of triggering the calibration routine, follow this procedure to set CAL SETUP (Point 95):

NOTE: The air velocity sensor must be calibrated at least once every 24 hours. Make sure that the sensor has been calibrated before balancing takes place as this will affect the balancer's results.

1. Display the first report in the REPORTS selection box.
2. Select an automatic calibration option from Table 7 that best meets your job requirements.
3. Set CAL SETUP to the value chosen.

Table 7. CAL SETUP Options.

CAL SETUP Options	Description
0	Calibration occurs ONLY when CAL AIR (Point 94) is set to YES.
1	Calibration occurs when the field panel commands a day/night mode changeover. Actual calibration is subject to a time delay of 0, 1, 2, or 3 minutes. This delay is determined by CTLR ADDRESS (Point 1) divided by 4 and the remainder is the time delay in minutes. Example: If CTLR ADDRESS = 11, then the controller waits 3 minutes ($11 \div 4 = 2 \text{ R}3$) after it receives the day/night mode changeover command before beginning the calibration routine.
2	Calibration occurs immediately after the override switch is pressed.
4 (factory default value)	Calibration occurs on the time interval set in CAL TIMER (Point 96). For example, if CAL TIMER = 12, then the calibration period is 12 hours. Actual calibration is subject to a time delay based on the value of CTLR ADDRESS. Refer to the example in Option 1. This is the recommended option when using a controller with an Autozero Module.

NOTE: Options can be combined by summing their Points. For example, to calibrate as in Options 1 and 2, set CAL SETUP to **3**.

Setting the Room Temperature Set Points

1. Display the SETPOINTS report.
2. If the room temperature sensor has a set point dial, and if RM STPT DIAL (Point 13) is to be used by the controller, then set the STPT DIAL (Point 14) to **YES**; otherwise, set STPT DIAL to **NO**.

NOTE: If STPT DIAL is set to YES, then the DAY HTG STPT (Point 7) and DAY CLG STPT (Point 6) will not be used. The value of RM STPT DIAL will be used.

3. If there is no set point dial on the room temperature sensor, then verify that STPT DIAL is set to **NO**.
4. Set the following points to the appropriate values:
 - DAY CLG STPT (Point 6)
 - DAY HTG STPT (Point 7)
 - NGT CLG STPT (Point 8)
 - NGT HTG STPT (Point 9)

4. If the room temperature sensor has a set point dial and the set point dial is to be used, then set RM STPT MIN (Point 11) and RM STPT MAX (Point 12) for the minimum and the maximum allowable room temperature set point values, respectively. Valid values range from 55° to 95°F (13° to 35°C). Common values are 65°F (18°C) for RM STPT MIN and 80°F (27°C) for RM STPT MAX.

Setting the Override Time

1. Display the STARTUP report.
2. If using night override, then set the OVRD TIME (Point 20) to the Point of whole hours that an override should last. If set at zero (the default), then night override is disabled.

Setting Controller Address

Set the controller address by setting the CTLR ADDRESS (Point 1) to the appropriate point.

Setting the Duct Area

1. Using the portable operator's terminal, press **F4** to display the **Duct Dimensions Menu**.
2. At the Duct Dimensions Menu, use the arrow keys to select the applicable duct shape. Press **ENTER**. The software prompts you for the dimensions of the duct.
3. Enter the dimensions as prompted. Press **ENTER** after each dimension you enter.

Setting the Flow Coefficient

1. Display the BALANCING report.
2. Set the FLOW COEFF (Point 36) to the appropriate value found in *Table 8, 9, or 10*. This value is a starting point for the air balancer.
3. To fine tune the flow coefficient, use the following formula:

$$\text{new flow coefficient} = (\text{actual volume} \div \text{TEC volume}) \times \text{old flow coefficient}$$

The actual volume is the actual value obtained from the balancer's measurements. The TEC volume is the value obtained from the AIR VOLUME (Point 35) of the TEC. If the TEC volume is not within 5% of the actual volume, then repeat the procedure until it is within 5%.

Table 8. Suggested TEC Initial Flow Coefficients for VAV Manufacturer and Box Sizes.

	Air velocity sensor type	Round ductwork (inlet) sizes in inches.												
		4	5	6	7	8	9	10	12	14	16	18	19	20
Anemostat	PX-2 cross, "P" range		0.77	0.74	0.75	0.78	0.74	0.81	0.81	0.85	0.80			
Anemostat	Traverse, "H" range		0.77	0.74	0.75	0.78	0.74	0.81	0.81	0.85	0.80			
Anemostat	PX-2 cross, "Q" range		0.56	0.51	0.56	0.57	0.59	0.60	0.64	0.65	0.72			
Anemostat	Traverse, "L" range		0.51	0.51	0.56	0.57	0.59	0.60	0.64	0.65	0.72			
Carrier	Linear averaging	0.75	0.71	0.64	0.63	0.62	0.62	0.61	0.61	0.58	0.54	0.58		
Carnes	"Standard sensor"		0.77	0.70	0.69	0.68		0.67	0.69	0.69	0.70			
Carnes	"Cross-flow sensor"		0.68	0.60	0.65	0.68		0.65	0.68	0.70	0.69			
Continental	AVS model "RSZ"			0.73		0.67		0.72	0.64	0.62	0.57		0.99	0.99
E.H. Price	CP101	1.04	0.83	0.64	0.68	0.66	0.72	0.75	0.80	0.85	0.80			
Environmental Tech.	sdr, vfr, cfr	0.79	0.78	0.59		0.62		0.64	0.65	0.66	0.66		0.59	0.66
Tuttle & Bailey/ SIEMENS	"Flo-cross" sensor (supply)	0.69	0.67	0.60	0.56	0.57		0.56	0.60	0.57	0.60	0.58		
Tuttle & Bailey/ SIEMENS	Flo-cross w/ total	0.59	0.55	0.50							0.51			
Tuttle & Bailey/ SIEMENS	Orifice ring flow sensor (exhaust)	0.70		0.70		0.75		0.75	0.67	0.67	0.67			
Krueger	General sensor	0.77	0.73	0.66	0.68	0.70	0.68	0.69		0.67				
Metal Ind. Fan powered only.	Fvi, fc, sv, rt, th, ct, dd (6 DO)									0.70	0.70			
Metal Ind. VAV & dual duct.	fvi, fc, sv, rt, th, ct, dd (6 DO)								0.50					
* Metal Ind. Dual duct only	fvi, fc, sv, rt, th, ct, dd (8 DO)			0.74		0.68		0.72						
Nailor Industries	Flow sensor	0.74		0.73		0.75		0.64						
Pottorff Inc.	TU-100			0.85		0.95		0.82	0.91	0.89	0.88			
Reddi-I-Inc.	Flowmaster			0.66		0.60		0.61	0.55	0.58	0.65			
Titus Inc.	Flowcross	0.92	0.81	0.63	0.61	0.64	0.62	0.63	0.64					
Trane (Rushville)	Air-valve (ring type)		0.64	0.60		0.64		0.65	0.65	0.65				
Tempmaster/York	All VAV, DD round	0.81	0.76		0.70	0.71		0.65	0.65	0.72	0.73			
Tempmaster/York	All VAV, DD Oval													
Warren Tech.	Kreuter SSS series			1.00		1.00		1.00	1.00	1.00	1.00			

* Inlet "Low Flow" air sensors should not be used if flow is less than 300 FPM.

NOTE: Refer to Voyager for additional flow coefficient information.

Table 9. Suggested TEC Initial Flow Coefficients for VAV manufacturer and Box Sizes.

	Air velocity sensor type	Rectangular ductwork (inlet) sizes in inches													
		4x7	4x10	6x9	6x12	6x15	8x11	8x14	8x17	8x20	8x24	9x12	9x14	19(-3)	22(-3)
Anemostat	PX-2 cross, "P" range														
Anemostat	Traverse, H" range														
Anemostat	PX-2 cross, "Q" range														
Anemostat	Traverse, "L" range														
Carrier	Linear averaging														
Carnes	"Standard sensor"											0.68			
Carnes	"Cross-flow sensor"											0.65			
Continental	AVS model "RSZ"														
E.H. Price	CP101														
***Environmental Tech.	sdr, vfr, cfr													0.61	0.64
Krueger	General sensor														
Metal Ind. Fan powered only.	Fvi ,fc, sv, rt, th, ct, dd (6 DO)														
Metal Ind. VAV & dual duct.	fvi, fc, sv, rt, th, ct, dd (6 DO)														
* Metal Ind. Dual duct only.	fvi, fc, sv, rt, th, ct, dd (8 DO)														
Nailor Industries	Flow sensor														
Pottorff Inc.	TU-100														
Reddi-I-Inc.	Flowmaster														
Titus Inc.	Flowcross														
Trane (Rushville)	Air-valve (ring type)														
Tempmaster/York	All VAV, DD round														
**Tempmaster/York	All VAV, DD Oval	0.72	0.73	0.73	0.73	0.72	0.73	0.74	0.72	0.72	0.74				
Warren Tech.	Kreuter SSS series														

* Inlet "Low Flow" air sensors should not be used if flow is less than 300 FPM.

** Tempmaster oval duct area and COF were calculated as rectangular duct shapes.

***ETI 19" has a rectangular area of 2.72 sq/ft. ETI 22" (32.25" x 15.875") rectangular area is 3.555 sq/ft.

NOTE: Refer to Voyager for additional flow coefficient information.

Table 10. Suggested TEC Initial Flow Coefficients for VAV manufacturer and Box Sizes.

	Air velocity sensor type	Rectangular ductwork (inlet) sizes In Inches									Oval sizes		
		12x14	12x16	12x18	12x28	12x24	16x18	16x24	16x28	20x26	12"	14"	16"
Anemostat	PX-2 cross, "P" range							0.79					
Anemostat	Traverse, "H" range												
Anemostat	PX-2 cross, "Q" range												
Anemostat	Traverse, "L" range												
Carrier	Linear averaging												
Carnes	"Standard sensor"						0.68	0.75					
Carnes	"Cross-flow sensor"						0.70	0.75					
Continental	AVS model "RSZ"												
E.H. Price	CP101		0.76					0.76					
Krueger	General sensor							0.71					
Metal Ind. Fan powered only.	fvi, fc, sv, rt, th, ct, dd												
	(6 DO)												
Metal Ind. VAV & dual duct.	fvi, fc, sv, rt, th, ct, dd	0.56	0.57	0.58	0.62	0.57				0.58	0.50	0.70	0.70
	(6 DO)												
* Metal Ind. Dual duct only	fvi, fc, sv, rt, th, ct, dd									0.60	0.64	0.67	0.68
	(8 DO)												
Nailor Industries	Flow sensor										0.58	0.63	0.68
Pottorff Inc.	TU-100							0.80					
Reddi-I-Inc.	Flowmaster												
Titus Inc.	Flowcross												
Trane(Rushville)	Air-valve (ring type)												
Tempmaster/York	All VAV, DD round												
**Tempmaster/York	All VAV, DD Oval												
Warren Tech.	Kreuter SSS series												

* Inlet "Low Flow" air sensors should not be used if flow is less than 300 FPM.

** Tempmaster oval duct area and COF were calculated as rectangular duct shapes.

NOTE: Refer to Voyager for additional flow coefficient information.

Setting MIN and MAX Airflow Set Points

NOTE: The maximum flow must be greater than or equal to the minimum flow.

Follow these steps to set the minimum and maximum airflow set points:

1. Set CLG FLOW MIN (Point 31) to the desired minimum cooling airflow set point.
2. Set CLG FLOW MAX (Point 32) to the desired maximum cooling airflow set point.
3. Set HTG FLOW MIN (Point 33) to the desired minimum heating airflow set point.
4. Set HTG FLOW MAX (Point 34) to the desired maximum heating airflow set point.

Enabling Wall Switch

If a wall switch is used for day/night control, then enable it by setting the WALL SWITCH (Point 18) to **YES**.

Disabling Autozero Module

Since the Autozero Module option is not available in this application, set CAL MODULE (Point 87) to **NO**.

Setting Maximum Induction Damper Position

Set IND DMPR MAX (Point 50) to the maximum position of the induction damper. This is the induction damper position when the flow is at minimum.

NOTE: Update each controller at the field panel immediately after you complete the controller start-up procedures, and have made all other changes to the controller's point database (including balancing, tuning, etc.).

The VAV with Induction Damper start-up is complete.